

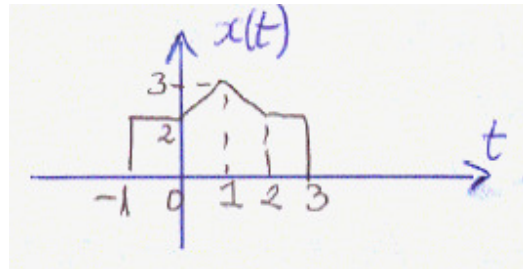
Fourier transform

Continuous-time Fourier transform (CTFT)

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega \xleftrightarrow{\mathcal{F}} X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt.$$

P1. Denote $X(\omega)$ – the Fourier transform of the signal $x(t)$. Determine the following values, without computing $X(\omega)$.

- $X(0)$
- $\int_{-\infty}^{\infty} X(\omega) d\omega$
- $\int_{-\infty}^{\infty} X(\omega) \frac{\sin \omega}{\omega} d\omega$
- $\int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$
- inverse Fourier transform for $\text{Re}\{X(\omega)\}$



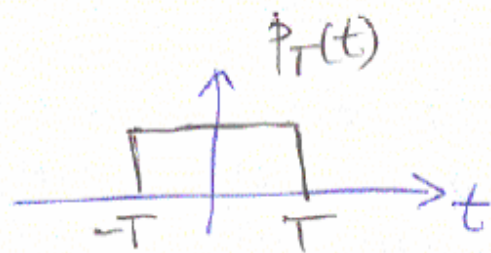
- From the definition $X(0) = \int_{-\infty}^{\infty} x(t) dt = 9$
- $\int_{-\infty}^{\infty} X(\omega) d\omega = 2\pi x(0) = 4\pi$
 $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega \stackrel{t=0}{=} 2\pi x(0) = 4\pi$
- $\int_{-\infty}^{\infty} X(\omega) \frac{\sin \omega}{\omega} d\omega = \int_{-\infty}^{\infty} Y(\omega) d\omega = 2\pi y(0)$

We denote $Y(\omega) = X(\omega) \frac{\sin \omega}{\omega}$

We know that:

$$p_T(t) \leftrightarrow X_p(\omega) = \frac{2 \sin \omega T}{\omega}$$

(from the table pairs signal-Fourier transform)



$$\Rightarrow Y(\omega) = X(\omega) \mathcal{F}\left\{\frac{1}{2} p_1(t)\right\}$$

$$\Rightarrow y(t) = x(t) * \left\{\frac{1}{2} p_1(t)\right\} = \frac{1}{2} \int_{-\infty}^{\infty} x(\tau) p_1(t-\tau) d\tau$$

$$\Rightarrow y(t) = \frac{1}{2} \int_{t-1}^{t+1} x(\tau) d\tau$$

$$y(0) = \frac{1}{2} \int_{-1}^1 x(\tau) d\tau = \frac{9}{4}$$

$$\int_{-\infty}^{\infty} X(\omega) \frac{\sin \omega}{\omega} d\omega = \int_{-\infty}^{\infty} Y(\omega) d\omega = 2\pi y(0) = 2\pi \frac{9}{4} = \frac{9\pi}{2}$$

d) $\int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$ - homework

Apply $\frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega = \int_{-\infty}^{\infty} |x(t)|^2 dt$

And from the sketched signal, we have the values of x(t):

$$x(t) = \begin{cases} 0, & t < -1 \\ 2, & -1 \leq t < 0 \\ t+2, & 0 \leq t < 1 \\ 4-t, & 1 \leq t < 2 \\ 2, & 2 \leq t < 3 \\ 0, & t > 3 \end{cases}$$

e) The inverse transform of $\text{Re}\{X(\omega)\}$ is $x_p(t) = \frac{x(t) + x(-t)}{2}$ - homework

P2. For a linear invariant time (LTI) system S with input signal x(t) and output signal y(t)

$$x(t) = [e^{-t} + e^{-3t}] \sigma(t); \quad y(t) = [2e^{-t} - 2e^{-4t}] \sigma(t)$$

- determine the frequency response of the system
- determine the impulse response of the system
- determine the differential equation ; implement the system using integrators, adders and multipliers

Solution.

a) $H(\omega) = ?$

$$H(\omega) = \frac{Y(\omega)}{X(\omega)}$$

$$x(t) = [e^{-t} + e^{-3t}] \sigma(t) \leftrightarrow X(\omega) = \frac{1}{1+j\omega} + \frac{1}{3+j\omega} = \frac{2(2+j\omega)}{(1+j\omega)(3+j\omega)}$$

$$y(t) = [2e^{-t} - 2e^{-4t}] \sigma(t) \leftrightarrow Y(\omega) = \frac{2}{1+j\omega} - \frac{2}{4+j\omega} = \frac{6}{(1+j\omega)(4+j\omega)}$$

$$\Rightarrow H(\omega) = \frac{3(3+j\omega)}{(4+j\omega)(2+j\omega)}$$

$$\text{b) } h(t) = ? \leftrightarrow H(\omega) = \frac{3(3+j\omega)}{(4+j\omega)(2+j\omega)} = \frac{A}{4+j\omega} + \frac{B}{2+j\omega}$$

$$A = H(\omega)(4+j\omega) \Big|_{j\omega=-4} = \frac{3(3+j\omega)}{(2+j\omega)} \Big|_{j\omega=-4} = \frac{3}{2}$$

$$B = H(\omega)(2+j\omega) \Big|_{j\omega=-2} = \frac{3(3+j\omega)}{(4+j\omega)} \Big|_{j\omega=-2} = \frac{3}{2}$$

$$\Rightarrow H(\omega) = \frac{3}{2} \left[\frac{1}{4+j\omega} + \frac{1}{2+j\omega} \right] \leftrightarrow h(t) = \frac{3}{2} [e^{-4t} + e^{-2t}] \sigma(t)$$

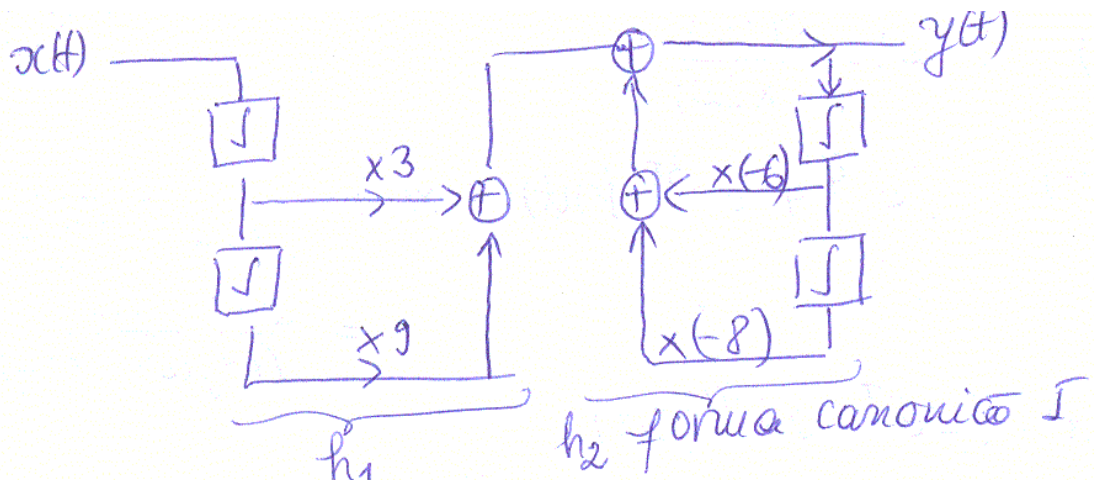
$$\text{c) } H(\omega) = \frac{3(3+j\omega)}{(4+j\omega)(2+j\omega)} = \frac{9+3j\omega}{8+6j\omega+(j\omega)^2} = \frac{Y(\omega)}{X(\omega)}$$

$$\Rightarrow 9X(\omega) + 3j\omega X(\omega) = 8Y(\omega) + 6j\omega Y(\omega) + (j\omega)^2 Y(\omega)$$

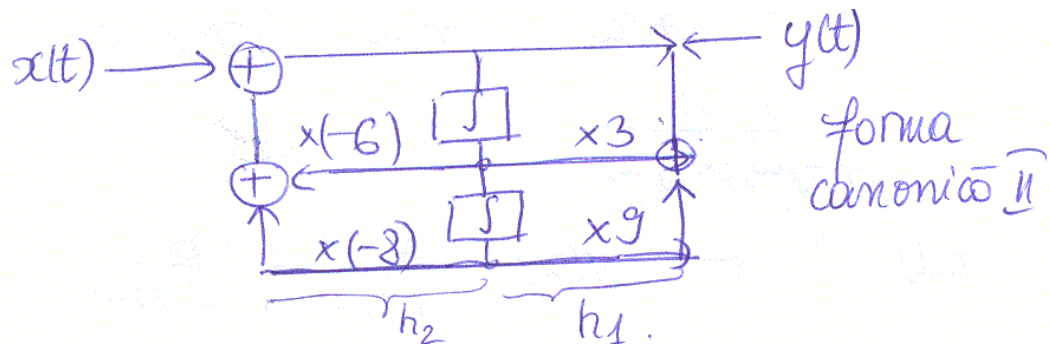
We have as property of Fourier transform: $(j\omega)^n X(\omega) \leftrightarrow \frac{d^n x(t)}{dt^n}$

$$\Rightarrow 9x(t) + 3x'(t) = 8y(t) + 6y'(t) + y''(t)$$

$$\Rightarrow 9 \int \left[\int x(t) dt \right] dt + 3 \int x(t) dt = 8 \int \left[\int y(t) dt \right] dt + 6 \int y(t) dt + y(t)$$



Canonical form I



Canonical form II

P3. The signal $x(t) = \cos \alpha t + \cos 3\alpha t$ is connected to the input of the system with the following impulse response (three cases):

$$h_a(t) = \frac{\sin(2\alpha t)}{\frac{\alpha}{2}t}; \quad h_b(t) = \frac{\sin(2\alpha t)\sin(4\alpha t)}{\frac{\alpha}{2}t^2}; \quad h_c(t) = \frac{\sin(2\alpha t)\cos(4\alpha t)}{\frac{\alpha}{2}t}$$

- Determine the frequency response of the system in the three cases. Sketch the corresponding magnitude spectra.
- Determine the response of the three systems to $x(t)$
- If $x(t)$ would have a useful component and a noisy component, which of the three systems would you pick, assuming the disturbance is $\cos(\alpha t)$? What if it's $\cos(3\alpha t)$?

Solution

a) $H_a(\omega), H_b(\omega), H_c(\omega) = ?$

From the table pairs signals-Fourier transform we have,

$$\frac{\sin(\omega_0 t)}{\pi t} \stackrel{\mathcal{F}}{\leftrightarrow} p_{\omega_0}(\omega) = \begin{cases} 1, & |\omega| < \omega_0 \\ 0, & |\omega| > \omega_0 \end{cases}$$

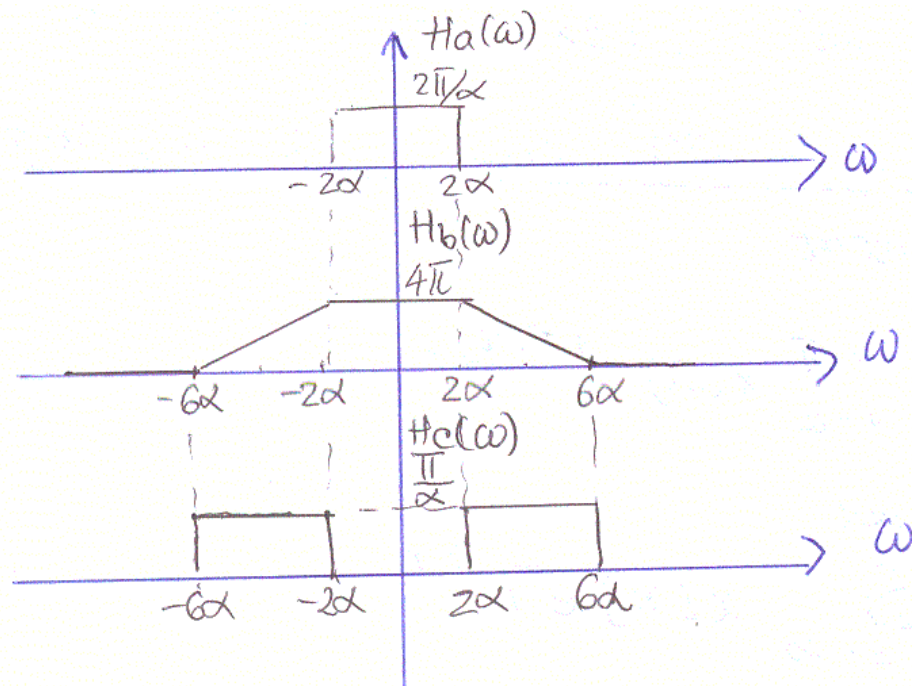
$$h_a(t) = \frac{2\pi \sin(2\alpha t)}{\alpha \pi t} \stackrel{\mathcal{F}}{\leftrightarrow} \frac{2\pi}{\alpha} p_{2\alpha}(\omega) = H_a(\omega)$$

$$\begin{aligned} h_b(t) &= \frac{2\pi^2 \sin(2\alpha t) \sin(4\alpha t)}{\alpha \pi t \pi t} \leftrightarrow \frac{2\pi^2}{\alpha} \cdot \frac{1}{2\pi} p_{2\alpha}(\omega) * p_{4\alpha}(\omega) \\ &= \frac{\pi}{\alpha} p_{2\alpha}(\omega) * p_{4\alpha}(\omega) = H_b(\omega) \end{aligned}$$

$$h_c(t) = \frac{\sin(2\alpha t) \cos(4\alpha t)}{\frac{\alpha}{2}t} = \frac{\sin(6\alpha t) - \sin(2\alpha t)}{2\frac{\alpha}{2}t}$$

$$\sin a \cos b = \frac{1}{2} [\sin(a+b) + \sin(a-b)]$$

$$h_c(t) = \frac{\pi}{\alpha} \left[\frac{\sin(6\alpha t)}{\pi t} - \frac{\sin(2\alpha t)}{\pi t} \right] \leftrightarrow H_c(\omega) = \frac{\pi}{\alpha} [p_{6\alpha}(\omega) - p_{2\alpha}(\omega)]$$



$$H_b(c) = \frac{\pi}{\alpha} \cdot \begin{cases} 0, & t < -6\alpha \\ 6\alpha + t, & -6\alpha \leq t < -2\alpha \\ 4\alpha, & -2\alpha \leq t < 2\alpha \\ 6\alpha - t, & 2\alpha \leq t < 6\alpha \\ 0, & t \geq 6\alpha \end{cases}$$

b) $y_a(t), y_b(t), y_c(t) = ?$

For $x(t) = \cos(\omega_0 t) \rightarrow y(t) = |H(\omega_0)| \cos(\omega_0 t + \arg\{H(\omega_0)\})$

$$x(t) = \cos \alpha t + \cos 3\alpha t$$

$$y(t) = |H(\alpha)| \cos(\alpha t + \arg\{H(\alpha)\}) + |H(3\alpha)| \cos(3\alpha t + \arg\{H(3\alpha)\})$$

For $H_a(\omega)$, we have the output signal

$$y_a(t) = |H_a(\alpha)| \cos(\alpha t + \arg\{H_a(\alpha)\}) + |H_a(3\alpha)| \cos(3\alpha t + \arg\{H_a(3\alpha)\})$$

$$\Rightarrow y_a(t) = \frac{2\pi}{\alpha} \cos(\alpha t)$$

In the same manner, we have

$$y_b(t) = 4\pi \cos(\alpha t) + 3\pi \cos(3\alpha t)$$

$$y_c(t) = \frac{\pi}{\alpha} \cos(3\alpha t)$$

Discrete-time Fourier transform (DTFT)

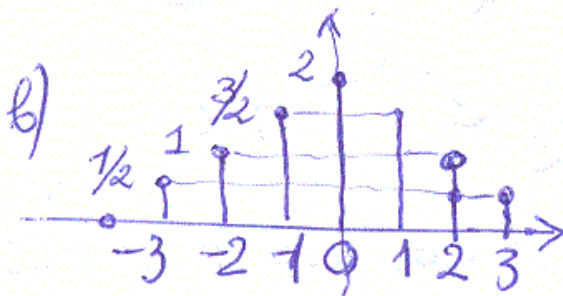
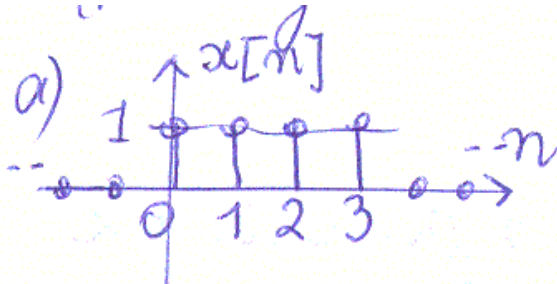
An aperiodic discrete-time signal can be decomposed in

$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\Omega) e^{j\Omega n} d\Omega$$

The Fourier transform

$$X(\Omega) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\Omega n}$$

P1. Determine the fourier transform for the following discrete-time signals



c) $x_3[n] = \left(\frac{1}{4}\right)^n \sigma[n+2]$

Solution.

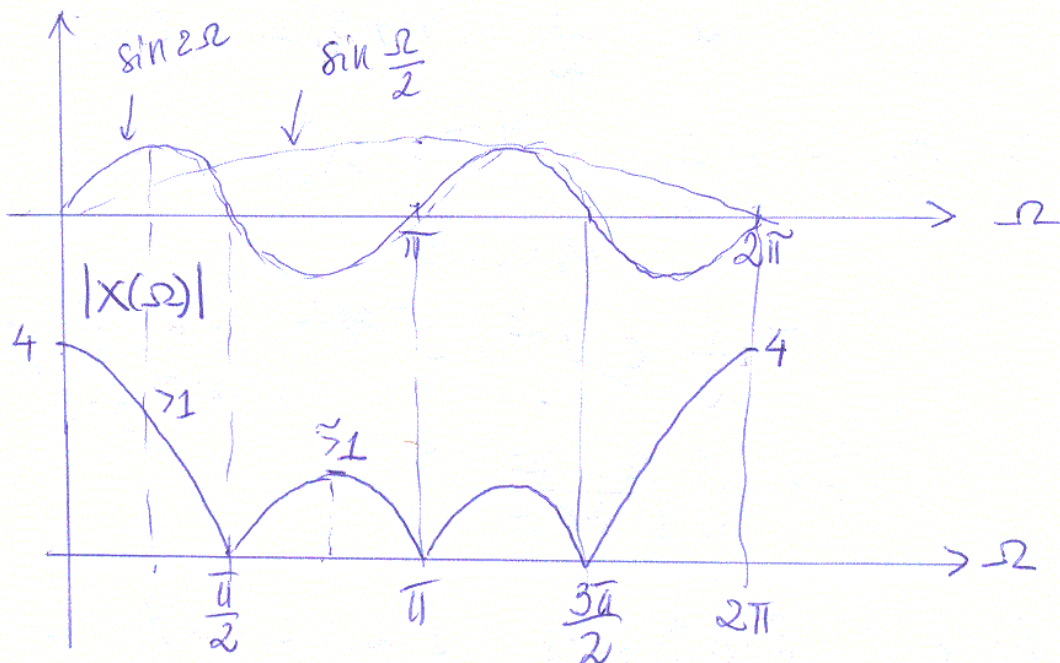
By definition, the DTFT is $X(\Omega) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\Omega n}$

a)

$$X(\Omega) = 1 \cdot e^0 + 1 \cdot e^{-j\Omega} + 1 \cdot e^{-2j\Omega} + 1 \cdot e^{-3j\Omega} = \frac{1 - e^{-4j\Omega}}{1 - e^{-j\Omega}} = \frac{e^{-2j\Omega} (e^{2j\Omega} - e^{-2j\Omega})}{e^{-j\frac{\Omega}{2}} (e^{j\frac{\Omega}{2}} - e^{-j\frac{\Omega}{2}})}$$

$$X(\Omega) = e^{-3j\frac{\Omega}{2}} \frac{2j \cdot \sin(2\Omega)}{2j \cdot \sin\left(\frac{\Omega}{2}\right)} = e^{-3j\frac{\Omega}{2}} \frac{\sin(2\Omega)}{\sin\left(\frac{\Omega}{2}\right)} \quad \begin{array}{l} \rightarrow T_1 = \pi \\ \rightarrow T_2 = 4\pi \end{array}$$

$$|X(\Omega)| = \frac{|\sin(2\Omega)|}{\left|\sin\left(\frac{\Omega}{2}\right)\right|}$$



b)

$$X_2(\Omega) = \frac{1}{2} \cdot e^{3j\Omega} + \frac{1}{2} \cdot e^{-3j\Omega} + 1 \cdot e^{2j\Omega} + 1 \cdot e^{-2j\Omega} + \frac{3}{2} \cdot e^{j\Omega} + \frac{3}{2} \cdot e^{-j\Omega} + 2$$

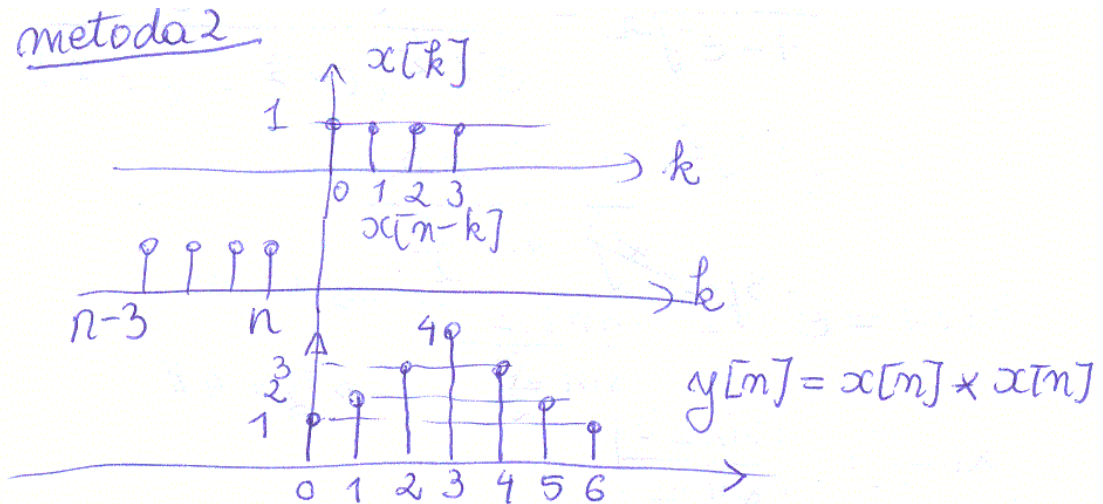
$$X_2(\Omega) = \frac{1}{2} \cdot 2 \cos(3\Omega) + 2 \cos(2\Omega) + \frac{3}{2} \cdot 2 \cos \Omega + 2$$

$$= 4 \cos^3 \Omega - 3 \cos \Omega + 2(2 \cos^2 \Omega - 1) + 3 \cos \Omega + 2$$

$$X_2(\Omega) = 4 \cos^3 \Omega + 4 \cos^2 \Omega = 4 \cos^2 \Omega (\cos \Omega + 1)$$

$$X_2(\Omega) = 4 \cos^2 \Omega \cdot 2 \cos^2 \frac{\Omega}{2} = 8 \cos^2 \Omega \cdot \cos^2 \frac{\Omega}{2}$$

Second method:



Notice that

$$\frac{1}{2} y[n+3] = x_2[n]$$

$$X_2(\Omega) = \frac{1}{2} \underbrace{e^{3j\Omega}}_{\text{shifting}} Y(\Omega) = \frac{1}{2} e^{3j\Omega} e^{-3j\Omega} \left(\frac{\sin 2\Omega}{\sin \frac{\Omega}{2}} \right)^2$$

$$X_2(\Omega) = \frac{1}{2} \left(\frac{\sin 2\Omega}{\sin \frac{\Omega}{2}} \right)^2$$

We can verify that the two results are the same:

$$8 \cos^2 \Omega \cdot \cos^2 \frac{\Omega}{2} = \frac{8 \cos^2 \Omega \cdot \cos^2 \frac{\Omega}{2} \cdot \sin^2 \frac{\Omega}{2}}{\sin^2 \frac{\Omega}{2}} = \frac{2 \cos^2 \Omega \cdot \sin^2 \Omega}{\sin^2 \frac{\Omega}{2}} = \frac{1}{2} \frac{\sin^2(2\Omega)}{\sin^2 \frac{\Omega}{2}}$$

c)

$$x_3[n] = \left(\frac{1}{4} \right)^n \sigma[n+2]$$

Direct computation

$$X_3(\Omega) = \sum_{n=-\infty}^{\infty} x_3[n] e^{-j\Omega n}$$

$$X_3(\Omega) = \left(\frac{1}{4}\right)^{-2} \cdot e^{2j\Omega} + \left(\frac{1}{4}\right)^{-1} \cdot e^{j\Omega} + \left(\frac{1}{4}\right)^0 \cdot 1 + \left(\frac{1}{4}\right)^1 \cdot e^{-j\Omega} + \left(\frac{1}{4}\right)^2 \cdot e^{-2j\Omega} + \left(\frac{1}{4}\right)^3 \cdot e^{-3j\Omega} + \dots$$

$$\begin{aligned} X_3(\Omega) &= \left(\frac{1}{4}\right)^{-2} \cdot e^{2j\Omega} \left[1 + \left(\frac{1}{4}\right) \cdot e^{-j\Omega} + \left(\frac{1}{4}\right)^2 \cdot e^{-2j\Omega} + \dots \right] \\ &= \left(\frac{1}{4}\right)^{-2} \cdot e^{2j\Omega} \frac{1}{1 - \frac{1}{4}e^{-j\Omega}} = \frac{16e^{2j\Omega}}{1 - \frac{1}{4}e^{-j\Omega}} \end{aligned}$$

From the table Pairs signals- Fourier transform

$$a^n \sigma[n] \leftrightarrow \frac{1}{1 - ae^{-j\Omega}}$$

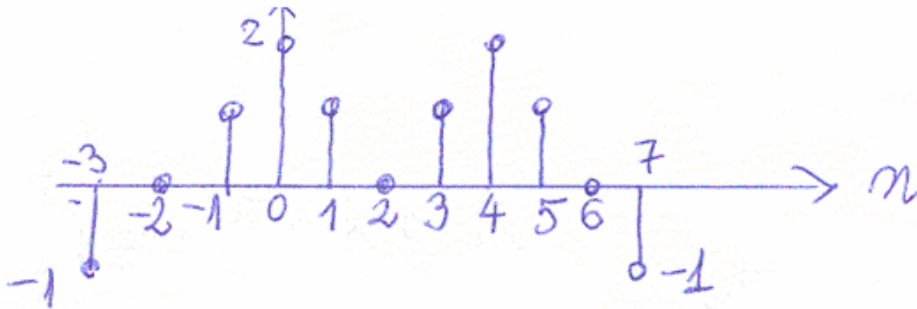
$$y[n] = x_3[n-2] = \left(\frac{1}{4}\right)^{n-2} \sigma[n] = 16 \left(\frac{1}{4}\right)^n \sigma[n]$$

$$Y(\Omega) = 16 \frac{1}{1 - \frac{1}{4}e^{-j\Omega}} = e^{-2j\Omega} X_3(\Omega)$$

$$\Rightarrow X_3(\Omega) = e^{2j\Omega} Y(\Omega) = \frac{16e^{2j\Omega}}{1 - \frac{1}{4}e^{-j\Omega}}$$

$$|X_3(\Omega)| = \frac{16}{\sqrt{\left(1 - \frac{1}{4}\cos\Omega\right)^2 + \left(\frac{1}{4}\sin\Omega\right)^2}} = \frac{16}{\sqrt{\frac{17}{16} - \frac{1}{2}\cos\Omega}}$$

P2. We have the signal x(t)



- $X(0)$
- $\arg\{X(\Omega)\}$
- $\int_{-\pi}^{\pi} X(\Omega) d\Omega$

- d) $X(\pi)$
 e) $\int_{-\pi}^{\pi} |X(\Omega)|^2 d\Omega$
 f) $\int_{2\pi} \left| \frac{dX(\Omega)}{d\Omega} \right|^2 d\Omega$
 g) inverse Fourier transform for $\text{Re}\{X(\Omega)\}$

Solution.

a) $X(\Omega) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\Omega n} \Rightarrow X(0) = \sum_{n=-\infty}^{\infty} x[n] = 6$

b) $\arg\{X(\Omega)\}$

Let $y[n] = x[n+2]$ - symmetrical - even signal $\Rightarrow Y(\Omega) \in R$

But $X(\Omega) = e^{-2j\Omega} Y(\Omega)$

$\arg\{X(\Omega)\} = -2\Omega + \arg\{Y(\Omega)\} = -2\Omega$

c) $I = \int_{-\pi}^{\pi} X(\Omega) d\Omega = ?$

$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\Omega) e^{j\Omega n} d\Omega$

$I = 2\pi x[0] = 4\pi$

d) $X(\Omega) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\Omega n} \Rightarrow X(\pi) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\pi n} = 2$, because $e^{-j\pi n} = (-1)^n$

e) $I = \int_{-\pi}^{\pi} |X(\Omega)|^2 d\Omega = 2\pi(1+1+4+1) \cdot 2$ because we have $\sum |x[n]|^2 = \frac{1}{2\pi} I$

f) $\int_{2\pi} \left| \frac{dX(\Omega)}{d\Omega} \right|^2 d\Omega$ -homework

Properties: $nx[n] \leftrightarrow j \frac{dX(\Omega)}{d\Omega} \Rightarrow \sum (nx[n])^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} \left| \frac{dX(\Omega)}{d\Omega} \right|^2 d\Omega$

g) The inverse Fourier transform of $\text{Re}\{X(\Omega)\}$ is $x_p[n] = \frac{x[n] + x[-n]}{2}$ -homework